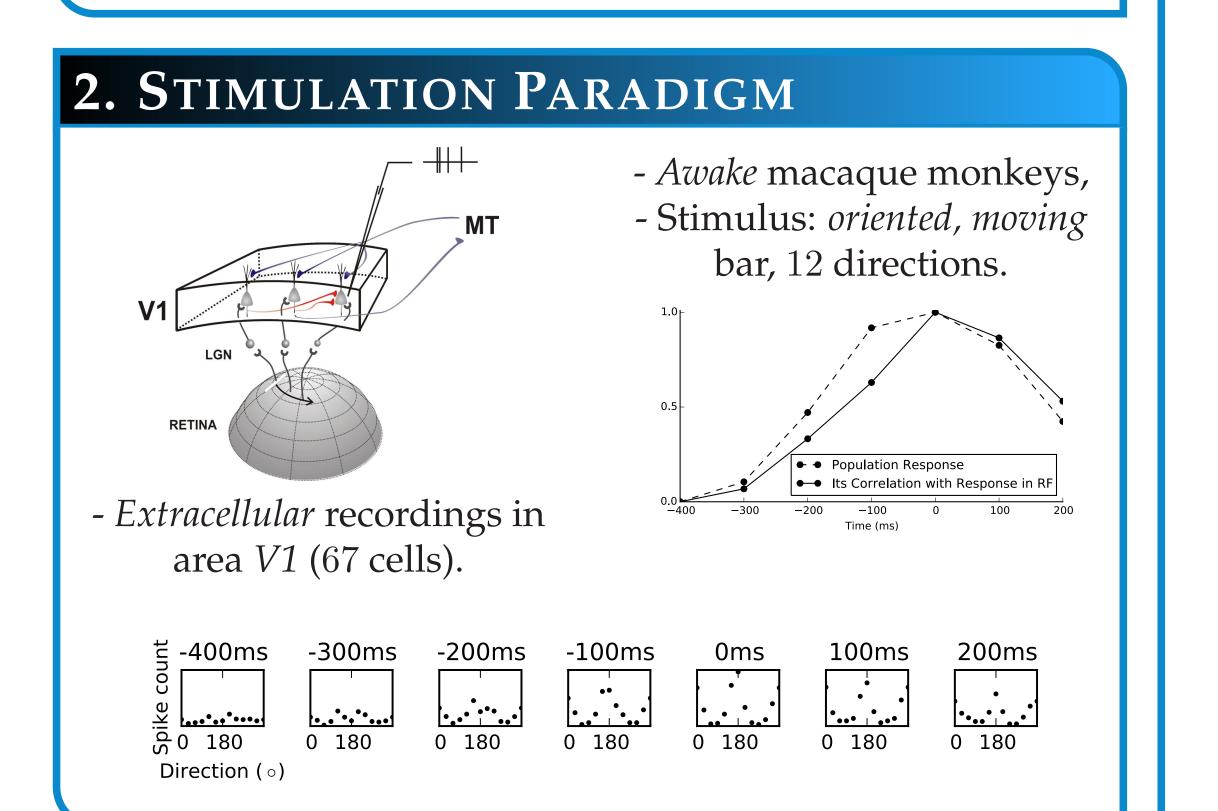


A DYNAMIC MODEL FOR DECODING DIRECTION AND ORIENTATION IN MACAQUE'S PRIMARY VISUAL CORTEX

1. MOTIVATION

- When an oriented moving bar reaches the classical receptive field (cRF) of V1 neurons, how are directional and orientational (tuning) information dynamically encoded in their activity?
- 2. How could this information be decoded from a V1 population, within and outside the cRF (while approaching or passing the RF)?



3. DECODING APPROACH [1]

1. Definition of a model for the inter-trial variability of spike counts. We use the Poisson model, which needs only one parameter, its mean μ_0 :

$$P(k) = \frac{\mu_0^k e^{-\mu_0}}{k!}$$
(1)

2. Estimation of the tuning function on the stimulus' parameters (orientation, direction, ...) : $f(\vartheta) = mean(k | \vartheta)$ such that :

$$P(k|\vartheta) = \frac{f(\vartheta)^k e^{-f(\vartheta)}}{k!}$$
(2)

3. Pooling of the population information assumes conditional independence:

$$P(Y|\vartheta) = \prod_{i=1}^{N} P(k_i|\vartheta), Y = [k_1, k_2..k_N]$$
(3)

- 4. Bayes' rule. $P(\vartheta|Y) = \frac{P(Y|\vartheta)P(\vartheta)}{P(Y)}$
- 5. Maximum likelihood paradigm

-The evidence term P(Y) is a normalization term independent of $\vartheta \to P(Y) = \operatorname{cst}$

-There is no prior knowledge on $\vartheta \to \forall (\vartheta_1, \vartheta_2), P(\vartheta_1) = P(\vartheta_2)$ \rightarrow Maximizing the posterior $P(\vartheta|Y)$ is equivalent to maximizing :

$$L(\vartheta) = P(Y|\vartheta) = \prod_{i=1}^{N} \frac{f_i(\vartheta)^{k_i} e^{-f_i(\vartheta)}}{k_i!}$$

6. Accuracy is computed using a 100-fold Leave One Out crossvalidation scheme.

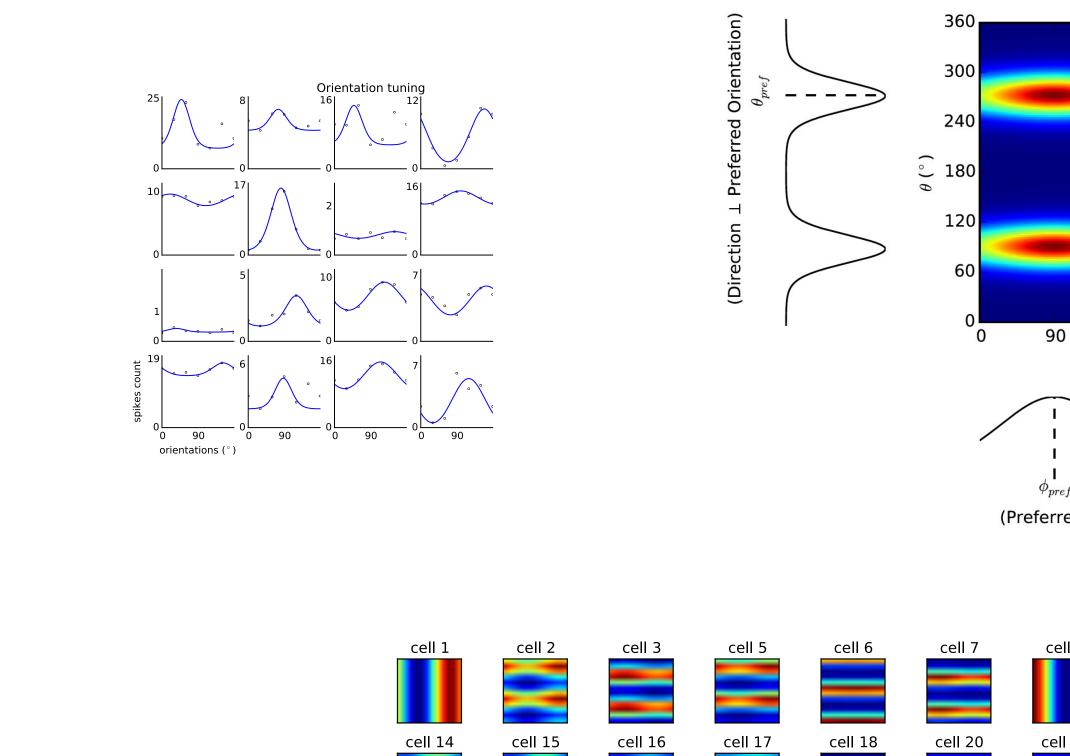
REFERENCES

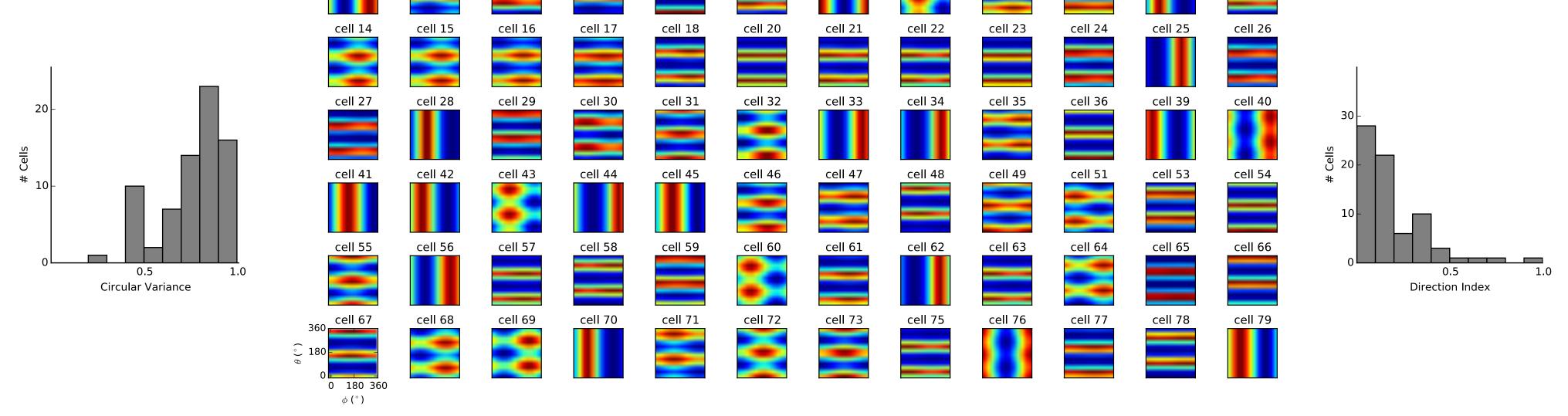
[1] M. Jazayeri and J.A. Movshon. Optimal representation of sensory information by neural populations. *Nature Neuroscience*, 9(5):690–696, 2006.

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4. GENERATIVE TUNING MODEL

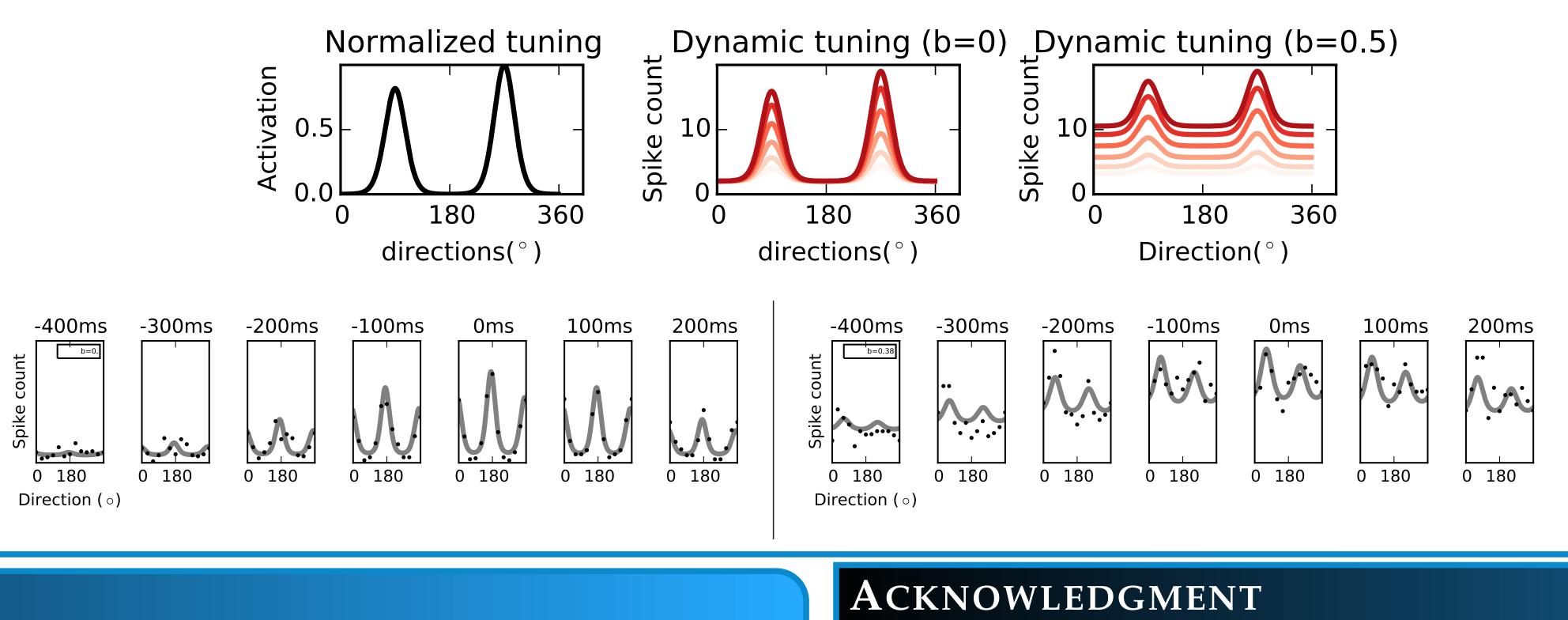
 $f(\phi, \theta) = R_0 + (R_m - R_0) \cdot e^{\kappa_{\theta} \cdot (\cos(2(\theta - \phi_0)) - 1)} \cdot e^{\kappa_{\phi} \cdot (\cos(\phi - \phi_0) - 1)}, \mathbf{D} \perp \mathbf{O} \rightarrow \phi = \theta$



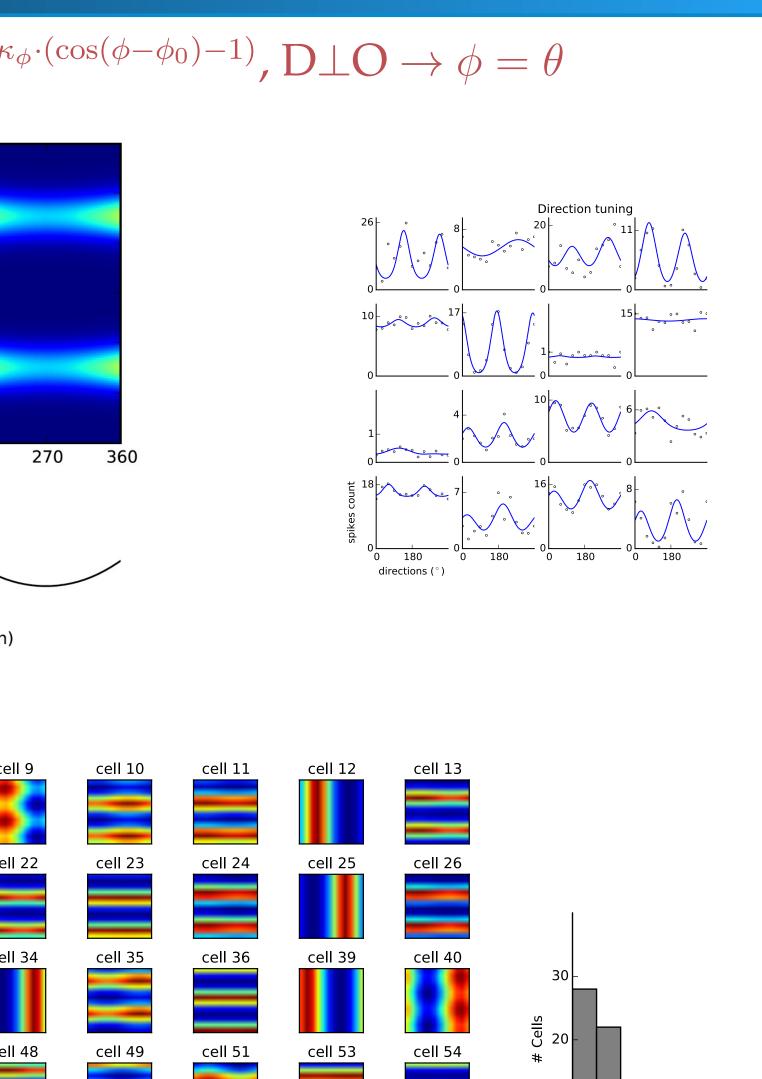


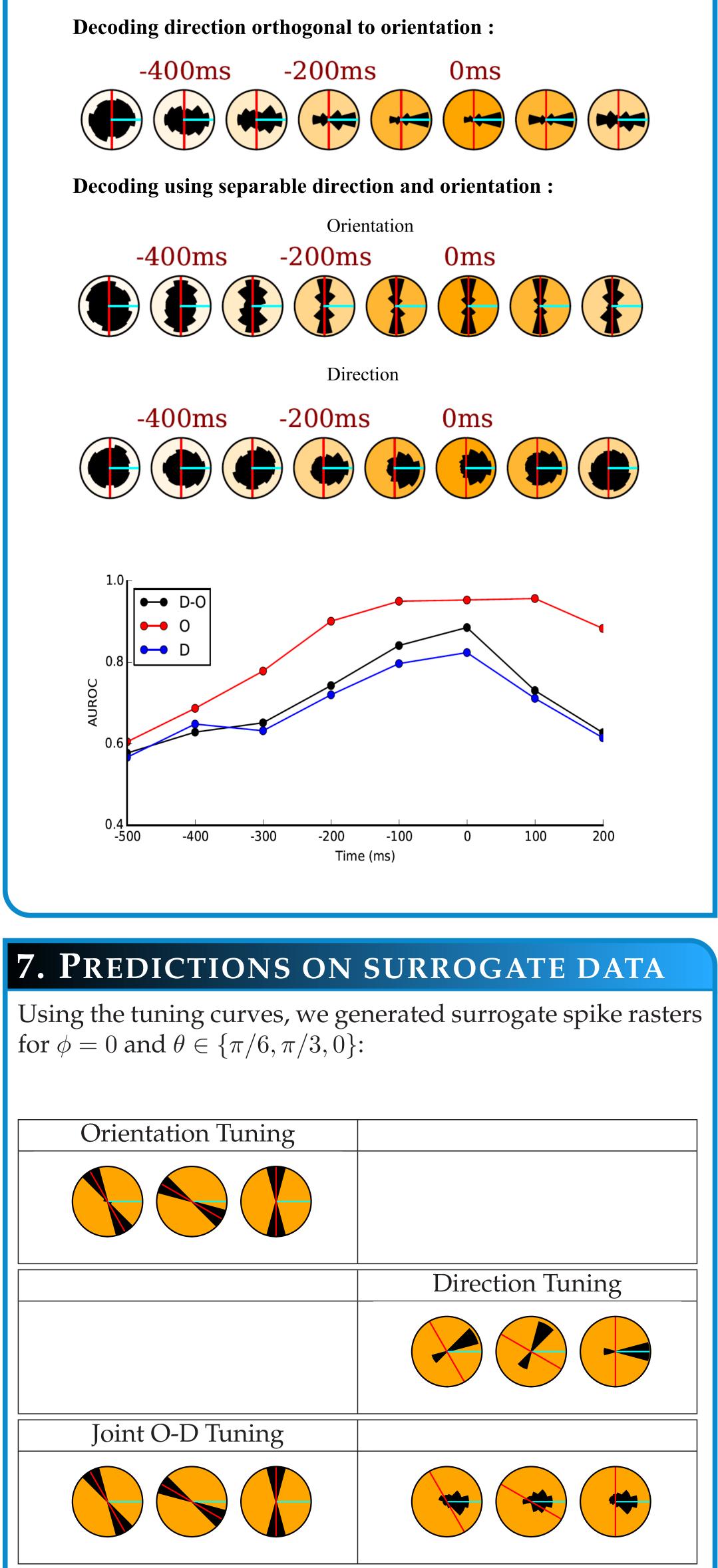
5. GENERATIVE MODEL OF DYNAMIC TUNING

 $\mathbf{f}(\phi, \theta, \mathbf{t}) = \mathbf{R}_{\mathbf{0}} + (\mathbf{R}_{\mathbf{m}} - \mathbf{R}_{\mathbf{0}}) \cdot \mathbf{A}(\mathbf{t}) \cdot (\mathbf{b} + (\mathbf{1} - \mathbf{b}) \cdot \mathbf{e}^{\kappa_{\theta} \cdot (\cos(\mathbf{2}(\theta - \phi_{\mathbf{0}})) - \mathbf{1})} \cdot \mathbf{e}^{\kappa_{\phi} \cdot (\cos(\phi - \phi_{\mathbf{0}}) - \mathbf{1})})$ with a Gaussian activation profile: $A(t) = \frac{1}{\sigma\sqrt{2\pi}}e^{\frac{-(t-\mu)^2}{2\sigma^2}}$ and a constant offset-to-gain ratio : b









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Direction Tuning